

Doubly Robust Calibration of Prediction Sets under Covariate Shift

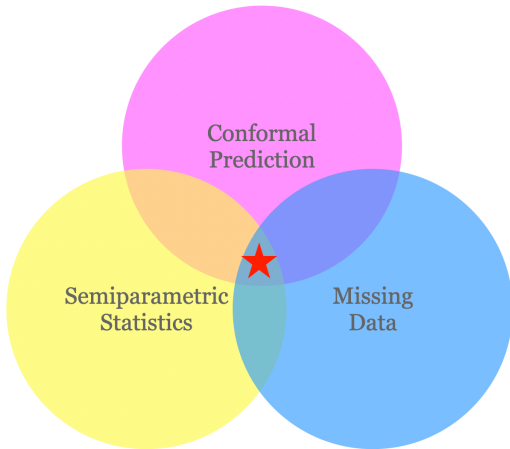
—the holy triad of
conformal prediction, semiparametrics, and missing data

Yachong Elsa Yang, University of Pennsylvania

Joint work with Prof. Arun Kumar Kuchibhotla, Carnegie Mellon University
Prof. Eric Tchetgen Tchetgen, University of Pennsylvania

<http://arxiv.org/abs/2203.01761>

Intersection of regimes



And many others:

- Covariate shift
- Transfer learning
- Causal inference
- ⋮

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Prediction Problems

Usual Prediction Problem

Given i.i.d. pairs $(X_i, Y_i) \sim P, i = 1, \dots, N$, for a distribution P on

$$\mathcal{X} \times \mathbb{R} \quad (\text{e.g. } \mathcal{X} = \mathbb{R}^d)$$

Goal. Build a prediction set \hat{C}_N , such that for new i.i.d. pair (X_{N+1}, Y_{N+1}) :

$$\mathbb{P} \left(Y_{N+1} \in \hat{C}_N(X_{N+1}) \right) \geq 1 - \alpha,$$

(where the probability is over all $N + 1$ pairs).

Conformal prediction provides a simple and finite-sample valid solution to this problem without any assumptions on P .

Such prediction sets can be **asymptotically efficient** (i.e., the smallest) too.

Today's talk: Prediction under Covariate Shift

- Suppose we have

$$\underbrace{(X_i, Y_i) \stackrel{iid}{\sim} P_X \otimes P_{Y|X}, 1 \leq i \leq n}_{\text{labeled data}} \quad \text{and} \quad \underbrace{X_i \stackrel{iid}{\sim} Q_X, n+1 \leq i \leq N}_{\text{unlabeled data}}.$$

- The covariate distribution in the unlabeled data, Q_X , is allowed to be different from that in the labeled data: **covariate shift**.

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- When $P_X = Q_X$, this relates to **semi-supervised learning**.

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Goal. Build a prediction set \hat{C}_N such that

$$\mathbb{P}(Y_f \in \hat{C}_N(X_f)) \geq 1 - \alpha, \quad (1)$$

whenever $(X_f, Y_f) \sim Q_X \otimes P_{Y|X}$.

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- This problem was first introduced by Tibshirani, Barber, Candès, Ramdas, *Conformal prediction under covariate shift*, 2020.

Connections to Missing data and Semiparametric theory

Missing Data Reformulation

- Choose and fix an arbitrary map $R(\cdot, \cdot)$ on $\mathcal{X} \times \mathbb{R}$. This is like a residual (**conformal score**), e.g. $|y - \hat{\mu}(x)|$, with $\hat{\mu}$ from an independent sample.
- For each (X_i, Y_i) with observed response, define $R_i = R(X_i, Y_i)$ and $T_i = 0$. If response is *unobserved*, then $T_i = 1$ and R_i also remains unobserved.
- The training data then are iid observations $(X_i, T_i, (1 - T_i)R_i)$ such that
 - $\mathbb{P}(X_i \in A | T_i = 0) =: P_X(A)$ and $\mathbb{P}(X_i \in A | T_i = 1) =: Q_X(A)$
 - $R_i \perp T_i | X_i$. This is the missing at random (MAR) assumption.

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 - $R_i \perp T_i | X_i$. This is the missing at random (MAR) assumption.
- Define r_α such that

$$\mathbb{P}(R_i \leq r_\alpha | T_i = 1) = 1 - \alpha. \quad (2)$$

- This implies that

$$\mathbb{P}_{(X, Y) \sim Q_X \otimes P_{Y|X}}(R(X, Y) \leq r_\alpha) = 1 - \alpha.$$

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$$\mathbb{P}_{(X, Y) \sim Q_X \otimes P_{Y|X}}(R(X, Y) \leq r_\alpha) = 1 - \alpha.$$

- Note that r_α is a semi-parametric functional here defined by (2).

Influence function and nuisance parameters

- Note that r_α satisfies

$$\mathbb{E}[\mathbb{P}(R_i \leq r_\alpha | T_i = 1, X_i)] = 1 - \alpha.$$

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- Hence r_α can be written in terms of two nuisance parameters:
 - one relating to **conditional distribution of R given X**

$$\begin{aligned} m^*(\gamma, x) &:= \mathbb{P}(R \leq \gamma | T = 1, X = x) \\ &= \mathbb{P}(R \leq \gamma | X = x); \end{aligned}$$

- one relating to **conditional distribution of T given X**

$$\pi^*(x) := \mathbb{P}(T = 1 | X = x) / \mathbb{P}(T = 0 | X = x).$$

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- The best way to estimate r_α is through the **efficient influence function**, which would give an estimator with second order (product) bias.

Double Robustness Property

- The **efficient influence function** for estimating r_α when the nuisance functions are π and m is

$$\begin{aligned} \text{IF}(\theta, x, r, t; \pi, m) &\propto \mathbb{1}\{t = 0\}\pi(x) \left[\mathbb{1}\{r \leq \theta\} - m(\theta, x) \right] \\ &\quad + \mathbb{1}\{t = 1\} \left[m(\theta, x) - (1 - \alpha) \right]. \end{aligned}$$

- This follows from the **semiparametric theory** and our **missing data reformulation** of the prediction problem under covariate shift.
- The connection to semiparametric theory also highlights the fact that our IF is **doubly robust**¹ for r_α in that

$$\mathbb{E}[\text{IF}(r_\alpha, X, R, T; \pi, m)] = 0, \quad \text{if either } \pi \equiv \pi^* \text{ or } m \equiv m^*.$$

- We are now ready to state our methodology for prediction under covariate shift.

¹James M. Robins and Heejung Bang (2005)

Methodology & Validity

Algorithm: Split Doubly Robust Prediction (Split-DRP)

Input: Data $(X_i, T_i, (1 - T_i)Y_i)$, $1 \leq i \leq N$, coverage probability $1 - \alpha$, a conformal score map $R(\cdot, \cdot)$, and estimators $\hat{\pi}$, \hat{m} , prediction point x .

1. Randomly split training data into two parts \mathcal{D}_1 and \mathcal{D}_2 each with $N/2$ observations.
2. Fit the estimators $\hat{\pi}$ and \hat{m} on the **first** split of the data and compute the conformal scores R_i on the **second** split of the data.
3. Solve for $\theta = \hat{r}_\alpha$ as the solution to $\mathbb{P}_{\mathcal{I}_2}[\text{IF}(\hat{\theta}, X, R, T; \hat{\pi}, \hat{m})] = 0$, where

$$\begin{aligned} \mathbb{P}_{\mathcal{I}_2}[\text{IF}(\hat{\theta}, X, R, T; \hat{\pi}, \hat{m})] &:= \frac{1}{N/2} \sum_{i \in \mathcal{D}_2} \mathbb{1}\{T_i = 0\} \hat{\pi}(X_i) [\mathbb{1}\{R_i \leq \hat{\theta}\} - \hat{m}(\hat{\theta}, X_i)] \\ &\quad + \frac{1}{N/2} \sum_{i \in \mathcal{D}_2} \mathbb{1}\{T_i = 1\} [\hat{m}(\hat{\theta}, X_i) - (1 - \alpha)]. \end{aligned}$$

4. **Output:** The prediction set $\hat{C}_\alpha := \{y : R(x, y) \leq \hat{r}_\alpha\}$.

Coverage Validity

Under i.i.d assumption, suppose estimators $\hat{\pi}, \hat{m}$ are bounded, then with probability at least $1 - \delta$,

$$\begin{aligned} \mathbb{P}_{(X,Y) \sim Q_X \otimes P_{Y|X}} \left(Y \in \hat{C}(\hat{r}_\alpha; X) \mid \mathcal{D}^{\text{tr}} \right) &\geq 1 - \alpha \\ &- \frac{\|\hat{\pi} - \pi^*\|_2 \sup_\theta \|\hat{m}(\theta, \cdot) - m^*(\theta, \cdot)\|_2}{\mathbb{P}(T = 1)} \\ &- \frac{e}{\mathbb{P}(T = 1)} \sqrt{\frac{\log(1/\delta)}{N}}. \end{aligned}$$

- First term is the target coverage;
- Second term is for estimating π^* and m^* ;
- Third term is for replacing the population expectation of IF with the sample expectation.

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The product bias term comes from the doubly robust IF.

Coverage Validity

PAC guarantee; With probability at least $1 - \delta$,

$$\begin{aligned} \mathbb{P}_{(X, Y) \sim Q_X \otimes P_{Y|X}} \left(Y \in \widehat{C}(\widehat{r}_\alpha; X) \mid \mathcal{D}^{\text{tr}} \right) &\geq 1 - \alpha \\ &- \frac{\|\widehat{\pi} - \pi^*\|_2 \sup_{\theta} \|\widehat{m}(\theta, \cdot) - m^*(\theta, \cdot)\|_2}{\mathbb{P}(\mathcal{T} = 1)} \\ &- \frac{\mathfrak{e}}{\mathbb{P}(\mathcal{T} = 1)} \sqrt{\frac{\log(1/\delta)}{N}}. \end{aligned}$$

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Unconditional coverage:

$$\begin{aligned} &\left| \mathbb{P}_{(X,Y) \sim Q_X \otimes P_{Y|X}} \left(Y \in \widehat{C}(\widehat{r}_\alpha; X) \right) - (1 - \alpha) \right| \\ &\leq \frac{\|\widehat{\pi} - \pi^*\|_2 \sup_{\theta} \|\widehat{m}(\theta, \cdot) - m^*(\theta, \cdot)\|_2}{\mathbb{P}(T = 1)} \\ &\quad + \frac{\mathfrak{e}}{\mathbb{P}(T = 1) \sqrt{N}}. \end{aligned}$$

Algorithm: Full Doubly Robust Prediction (Full-DRP)

Input: Data $(X_i, T_i, (1 - T_i)Y_i)$, $1 \leq i \leq N$, coverage probability $1 - \alpha$, a conformal score map $R(\cdot, \cdot)$, and estimators $\hat{\pi}, \hat{m}$, prediction point x .

1. Fit the estimators $\hat{\pi}$ and \hat{m} on the training data and compute the conformal scores R_i for each $i \in [N]$.
2. Solve for $\theta = \hat{r}_\alpha$ as a solution to $\mathbb{P}_N[\text{IF}(\hat{\theta}, X, R, T; \hat{\pi}, \hat{m})] = 0$, where

$$\begin{aligned} \mathbb{P}_N[\text{IF}(\hat{\theta}, X, R, T; \hat{\pi}, \hat{m})] &:= \frac{1}{N} \sum_{i=1}^N \mathbb{1}\{T_i = 0\} \hat{\pi}(X_i) [\mathbb{1}\{R_i \leq \hat{\theta}\} - \hat{m}(\hat{\theta}, X_i)] \\ &\quad + \frac{1}{N} \sum_{i=1}^N \mathbb{1}\{T_i = 1\} [\hat{m}(\hat{\theta}, X_i) - (1 - \alpha)]. \end{aligned}$$

3. **Output:** The prediction set $\hat{C}_\alpha := \{y : R(x, y) \leq \hat{r}_\alpha\}$.

Simulations: Comparison between methods

Mean coverage and width from 500 monte carlo runs	Synthetic data		Real data	
	Coverage	Width	Coverage	Width
DRP w. full data	0.90	3.29	0.94	27.85
DRP w. splitting	0.90	3.30	0.90	25.79
WCP ²	0.97	7.41	0.99	47.71

Table 1: Coverage and width of DRP and WCP on synthetic and real data.

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- WCP produces wider width and therefore, tends to over cover by a considerable amount (by more than 7% over the nominal coverage of 90%). See [appendix](#) for a description on WCP.

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- WCP produces wider width and therefore, tends to over cover by a considerable amount (by more than 7% over the nominal coverage of 90%). See [appendix](#) for a description on WCP.
- Doubly robust prediction with full data and multiple splits have similar performance with valid coverage.

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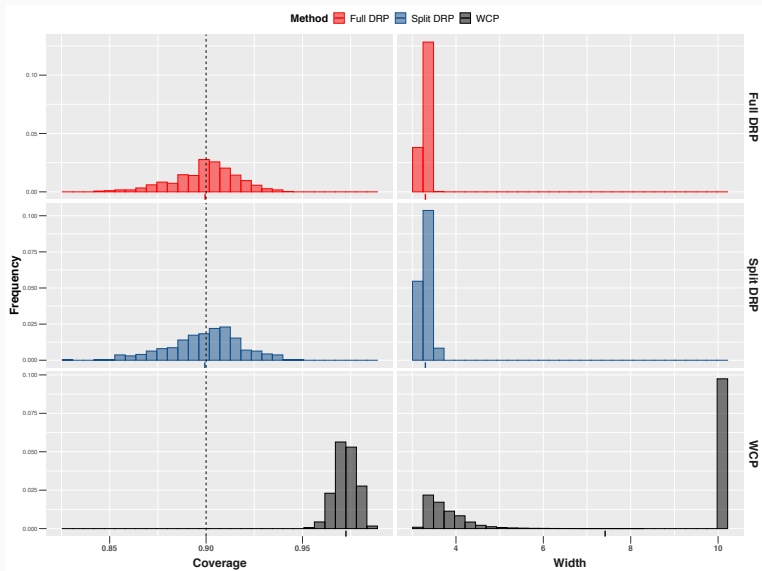


Figure 1: Coverage and width comparison on synthetic data

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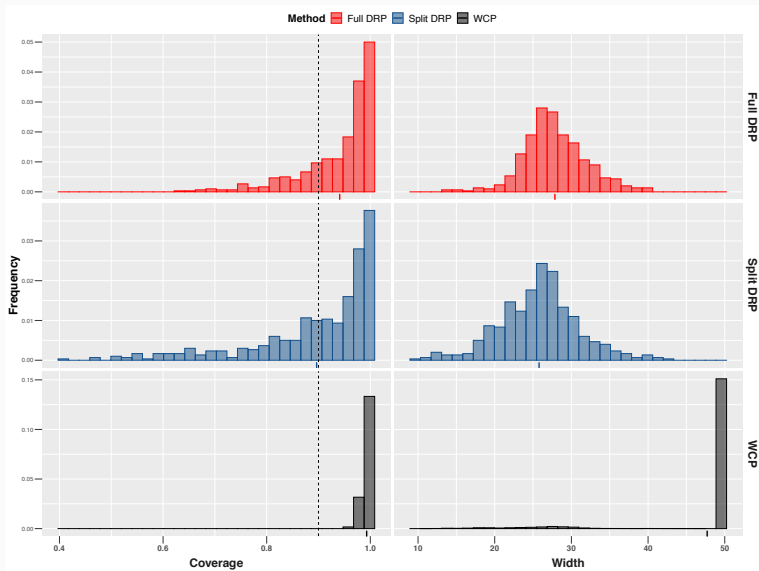


Figure 2: Coverage and width comparison on real data

Comparison with existing works & Extensions

Comparison with existing works

Our method

- Our method does not depend on the test point (new x) at which prediction is needed.
- Our method has double robustness for arbitrary conformal score and the coverage is guaranteed for any training method.
- The bias of our coverage is a product of two errors.

Weighted conformal prediction Tibshirani et al. 2020

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- This method *requires* the test point (new x) to be specified in advance.
[Lei and Candès, 2021](#)
- Their result on double robustness holds only under a specific conformal score: conformal quantile regression (CQR).
- The bias of their coverage is the minimum (not product) of two errors.

- This method can be combined with our previous work on efficiency first conformal prediction (EFCP)³ to choose the prediction interval with the minimum width.

³Yang and Kuchibhotla (2021)

- This method can be combined with our previous work on efficiency first conformal prediction (EFCP)³ to choose the prediction interval with the minimum width.
- It can also be extended to provide prediction intervals for counterfactuals and individual treatment effects (ITE), following Lei and Candès (2021).

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- This method can be combined with our previous work on efficiency first conformal prediction (EFCP)³ to choose the prediction interval with the minimum width.
- It can also be extended to provide prediction intervals for counterfactuals and individual treatment effects (ITE), following Lei and Candès (2021).
- We can relax the MAR assumption to MNAR (corresponding to *Unconfoundedness* condition in Causal) using **sensitivity analysis**.

³Yang and Kuchibhotla (2021)

Prediction intervals for counterfactuals and individual treatment effects (ITE)

Causal inference and Counterfactuals

Given N subjects, let $T_i \in \{0, 1\}$ be a binary treatment indicator, $(Y_i(1), Y_i(0))$ be the pair of potential outcomes, and X_i be the covariates.

- Assume $(Y_i(1), Y_i(0), T_i, X_i) \stackrel{\text{i.i.d.}}{\sim} (Y(1), Y(0), T, X)$

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- Predict individual treatment effect (ITE) $\tau_i := Y_i(1) - Y_i(0)$, **unobserved**

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- Predict individual treatment effect (ITE) $\tau_i := Y_i(1) - Y_i(0)$, **unobserved**
- For any treated unit i in the study, i.e. with $T_i = 1$, we construct a prediction interval \hat{C}_i^{ITE} for τ_i such that $\hat{C}_i^{\text{ITE}} = Y_i^{\text{obs}} - \hat{C}_0(X_i)$, where $\hat{C}_0(x)$ satisfies

$$\mathbb{P}(Y(0) \in \hat{C}_0(X) \mid T = 1) \geq 1 - \alpha; \quad (3)$$

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$$\mathbb{P}(Y(0) \in \hat{C}_0(X) \mid T = 1) \geq 1 - \alpha; \quad (3)$$

- Such construction has guaranteed coverage⁴ for τ_i ,

$$\mathbb{P}(Y_i(1) - Y_i(0) \in \hat{C}_i^{\text{ITE}}) \geq 1 - \alpha.$$

⁴See **proof** in appendix.

Relaxing the distribution shift (MAR) assumption

The original covariate shift problem

- Suppose we have

$$\underbrace{(X_i, Y_i) \stackrel{iid}{\sim} P_X \otimes P_{Y|X}, 1 \leq i \leq n}_{\text{labeled data}} \quad \text{and} \quad \underbrace{X_i \stackrel{iid}{\sim} Q_X, n+1 \leq i \leq N}_{\text{unlabeled data}}.$$

- The covariate distribution in the unlabeled data, Q_X , is allowed to be different from that in the labeled data: **covariate shift**.

Goal. Build a prediction set \hat{C}_N such that

$$\mathbb{P}(Y_f \in \hat{C}_N(X_f)) \geq 1 - \alpha, \quad (4)$$

whenever $(X_f, Y_f) \sim Q_X \otimes P_{Y|X}$.

Relaxing the covariate shift assumption

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Goal. Build a prediction set \hat{C}_N such that

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$$\mathbb{P}(Y_f \in \hat{C}_N(X_f)) \geq 1 - \alpha, \quad (5)$$

whenever $(X_f, Y_f) \sim Q_X \otimes Q_{Y|X}$.

Suppose we want to relax the $P_{Y|X} = Q_{Y|X}$ assumption,

$$\exp(\gamma(x, y)) = \frac{P_{Y=y|X=x}}{Q_{Y=y|X=x}} \frac{Q_{Y=y_0|X=x}}{P_{Y=y_0|X=x}},$$

where $\gamma(x, y)$ is a known sensitivity analysis function which satisfies $\gamma(x, y_0) = 0$ for any baseline y_0 .

Sensitivity analysis

Sensitivity function:⁵

$$\exp(\gamma(x, y)) = \frac{P_{Y=y|X=x}}{Q_{Y=y|X=x}} \frac{Q_{Y=0|X=x}}{P_{Y=0|X=x}}.$$

As a special case when $\gamma(x, y) = 0$, this goes back to the original covariate shift problem.

⁵James M. Robins, Andrea Rotnitzky, and Daniel O. Sharpstein (1999)

Sensitivity analysis

Sensitivity function:⁵

$$\exp(\gamma(x, y)) = \frac{P_{Y=y|X=x} Q_{Y=0|X=x}}{Q_{Y=y|X=x} P_{Y=0|X=x}}.$$

As a special case when $\gamma(x, y) = 0$, this goes back to the original covariate shift problem. An equivalent way is using the missing data notation:

$$\gamma(x, y) = \log \frac{\mathbb{P}(T = 0|X = x, Y = y)\mathbb{P}(T = 1|X = x, Y = 0)}{\mathbb{P}(T = 0|X = x, Y = 0)\mathbb{P}(T = 1|X = x, y)}.$$

⁵James M. Robins, Andrea Rotnitzky, and Daniel O. Shafstein (1999)

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The efficient influence function is given by

$$\begin{aligned} & \text{IF}(r_\alpha, x, y, r, t; \eta^*, m^*, \gamma^*) \\ & \propto \mathbb{1}\{t = 0\} \frac{\mathbb{P}(T = 1|X = x, Y = y)}{\mathbb{P}(T = 0|X = x, Y = y)} \left[\mathbb{1}\{r \leq r_\alpha\} - \mathbb{P}(R \leq r_\alpha|X = x, T = 1) \right] \\ & \quad + \mathbb{1}\{t = 1\} \left[\mathbb{P}(R \leq r_\alpha|X = x, T = 1) - (1 - \alpha) \right]. \end{aligned}$$

(6)

⁵James M. Robins, Andrea Rotnitzky, and Daniel O. Sharpstein (1999)

Double robustness and nuisance functions

Formally, let $\gamma^*(x, y)$ be the sensitivity function defined by

$$\gamma^*(x, y) = \log \frac{\mathbb{P}(T = 0|X = x, Y = y)\mathbb{P}(T = 1|X = x, Y = 0)}{\mathbb{P}(T = 0|X = x, Y = 0)\mathbb{P}(T = 1|X = x, y)},$$

and denote two nuisance functions by

$$\begin{cases} \eta^*(x) := \log \frac{\mathbb{P}(T=0|X=x, Y=0)}{\mathbb{P}(T=1|X=x, Y=0)}; \\ m^*(\theta, x) := \mathbb{P}(R \leq \theta | X = x, T = 1). \end{cases} \quad (7)$$

$\text{IF}(r_\alpha, x, y, r, t; \eta, m, \gamma^*)$ satisfies the double robustness property that

$$\mathbb{E}[\text{IF}(r_\alpha, x, y, r, t; \eta, m, \gamma^*)] = 0, \quad (8)$$

if either $\eta = \eta^*$ or $m = m^*$.

Note that the two nuisance parameters **can not be directly estimated from data**:

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Estimating nuisance functions

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Ghassami et al. (2021)⁶ provides a general framework to estimate nuisance parameters, that can establish the regularity and asymptotic normality of the doubly robust estimator of r_α , see [appendix](#).

⁶AmirEmad Ghassami, Andrew Ying, Ilya Shpitser, and Eric Tchetgen Tchetgen (2021)

Comparison with existing works on sensitivity analysis

Our method

- Our method does not depend on the test point (new x) at which prediction is needed.
- Our method has double robustness for arbitrary conformal score and the coverage is guaranteed for any training method.
- The bias of our coverage is a product of two errors.

Jin, Ren and Candès, 2021

- A different sensitivity framework.

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Robust conformal prediction: the PAC procedure

- Depends on an addition parameter δ .

Take home message

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Thank You!

<http://arxiv.org/abs/2203.01761>

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Appendix

Weighted Conformal Prediction

In the weighted conformal prediction method, the prediction interval is given by

$$\widehat{C}_n(x) = \mu_0(x) \pm \text{Quantile} \left(1 - \alpha; \sum_{i=1}^n p_i^w(x) \delta_{|Y_i - \mu_0(x_i)|} + p_{n+1}^w(x) \delta_\infty \right), \quad (10)$$

where $p^w(x)$ depends on the likelihood ratio between P_X and Q_X , or $\pi^*(x)$.

- When the distribution shift is too “large”, i.e. $p_{n+1}^w(x)$ is larger than α , the width becomes ∞ .

Coverage for ITE:

$$\begin{aligned} & \mathbb{P}(Y_i(1) - Y_i(0) \in \widehat{C}_i^{\text{ITE}}) \\ &= \mathbb{P}(T_i = 1)\mathbb{P}(Y_i(0) \in \widehat{C}_0(X_i) | T_i = 1) + \mathbb{P}(T_i = 0)\mathbb{P}(Y_i(1) \in \widehat{C}_1(X_i) | T_i = 0) \\ &\geq (1 - \alpha)(\mathbb{P}(T_i = 1) + \mathbb{P}(T_i = 0)) \\ &= 1 - \alpha. \end{aligned}$$

Estimating nuisance parameters

Leverage a doubly robust influence function such as $\text{IF}(\cdot \cdot \cdot)$ to generate an objective function for each nuisance parameter.

Specifically, in the case where one specifies $\mu = \exp(-\eta)$ and m as elements of Reproducing Kernel Hilbert Spaces \mathcal{R} and \mathcal{M} equipped with the RKHS norms $\|\cdot\|_{\mathcal{R}}$ and $\|\cdot\|_{\mathcal{M}}$ respectively,

$$\hat{\mu} = \arg \min_{\mu \in \mathcal{R}} \sup_{m \in \mathcal{M}} \mathbb{P}_N \left\{ m(\theta, X) [-\mu(x) \exp(-\gamma^*(X, Y)) \mathbb{1}\{T=0\} + \mathbb{1}\{T=1\}] - m^2(\theta, X) \right\} - \lambda_{\mathcal{M}}^q \|m\|_{\mathcal{M}}^2 + \lambda_{\mathcal{R}}^q \|\mu\|_{\mathcal{R}}^2;$$

$$\hat{m} = \arg \min_{m \in \mathcal{M}} \sup_{\mu \in \mathcal{R}} \mathbb{P}_N \left\{ -\mu(X) \exp(-\gamma^*(X, Y)) \mathbb{1}\{T=0\} [m(\theta, X) - \mathbb{1}\{R \leq \theta\}] - \mu^2(X) \right\} - \lambda_{\mathcal{R}}^m \|\mu\|_{\mathcal{R}}^2 + \lambda_{\mathcal{M}}^m \|m\|_{\mathcal{M}}^2,$$

where hyper parameters $\lambda_{\mathcal{M}}^q$, $\lambda_{\mathcal{R}}^q$, $\lambda_{\mathcal{R}}^m$, and $\lambda_{\mathcal{M}}^m$, as well as the kernel bandwidth are chosen by cross validation.